

Mission Statement

The CMOS Solar-Powered Battery Charger is a unique approach to solve the rapidly growing need for more renewable energy sources and sustainable practices in our ever-evolving world. This design would enable both the usage of clean solar energy for charging and increase the usage of rechargeable batteries, eliminating the single-use batteries that currently plague many of our landfills and devices.

This Battery Charger can be implemented to charge small batteries which can power devices such as: Small Sensor Devices, Glucose Monitors, and RFID Tags

Design Goals and Constraints

- Create a Battery Charger Circuit that can perform trickle charging, constant current charging, and constant voltage charging
- Design the Circuits for maximum efficiency
- No external power supplies, all power must come from the solar cell • Limited to chip area of 1mm²
- Maintain IEEE standards std. 2405-2022 and std. 1725-2021, to ensure optimal performance, and to maintain best practices
- Ensure that the battery charging circuitry complies with the battery manufacturer's specifications (maximum current and voltage)



CMOS Solar-Powered Battery Charger Joseph Jacob, Thomas Lipetzky, Price Nguyen, Vincent Tan

CMOS Circuits



Comparator circuit outputs 1.8V whenever voltage on + exceeds voltage on -. Used for ramp generation and the final PWM output







Differential amplifier (left) is used to read in the output voltage of boost converter and a reference voltage, amplify it, and use that value to control the duty cycle of the boost converter. Operational amplifier (right) works similar with the differential amplifier, except it integrates and amplifies the difference. Both of these circuits are combined together to create our PI controller



Battery Charger Circuit (Right), this circuit is used to supply the charging modes to the battery. This is done using the Charging Mode Controllers, which send an on/off signal to a series of current mirrors to add or remove current from the output. Additionally,

the Battery Charger Contains an



Overcharge Controller, which prevent the overcharging of the battery if it is already full.

Boost Converter Equations

$$H(S) = \frac{\left(-\frac{sI_L}{C} + \frac{V_{out}D'}{LC}\right)}{s^2 + \frac{s}{RC} + \frac{{D'}^2}{LC}}$$

Equation for calculating the size of the inductor for the boost converter. Vin is the input voltage, Vout is the output voltage IL is the current ripple, and fs is the switching frequency.

$$C_{OUT(min)} = \frac{I_{OUT(max)} \times D}{f_{S} \times \Delta V_{OUT}}$$

From this transfer function detailing the dynamics across frequencies, we see marginal stability but with very light damping and large oscillations Our controller has to further dampen the oscillations



Equation for calculating the size of the capacitor for the boost converter. lout is the output current, D is the Duty cycle, fs is switching frequency, and Vout is output voltage



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Simulation Results

Output of the PWM generator, We compare the ramp signal (blue) with the constant duty control voltage (tan). Every time the constant signal exceeds the ramp, the PWM signal (purple) goes high



Output voltage of the boost converter





References

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